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... represent the horizontal and vertical position of a ... of a larger set that affect the range values. ... Selection of an appropriate light source depends primarily on ...

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... The range of this system is 40 ft. 3.4. ... For this a global positioning sys- tem (GPS) is used to get the original robot position, ... 3.5.1. GPS Selection ...

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... including display surfaces, object tracking, **selection**, navigation, graphics ... here  
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